

Mathematical tools for pharmacometrics: Linear algebra

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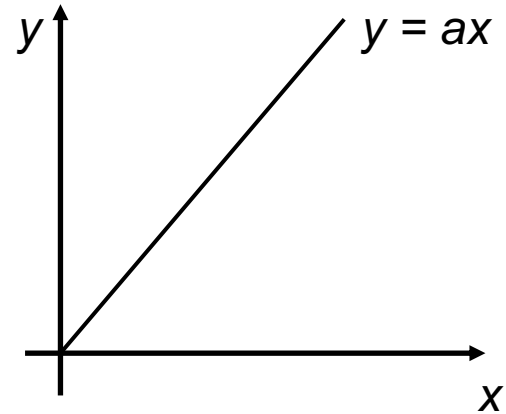
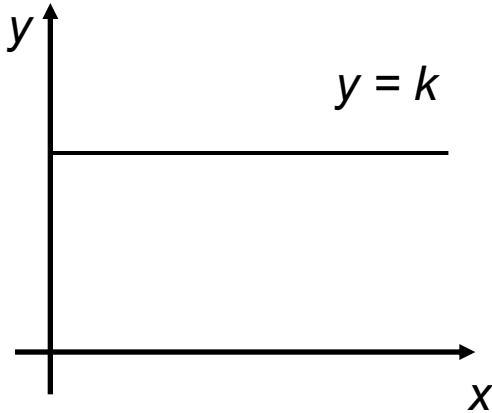
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SMART_c
SIMULATION MODELING ADAPTIVE RESPONSE
FOR THERAPEUTICS IN CANCER

Linearity: the simplest mathematical relationship

- Variable y (ex: concentration max) that depends on variable x (ex: dose)



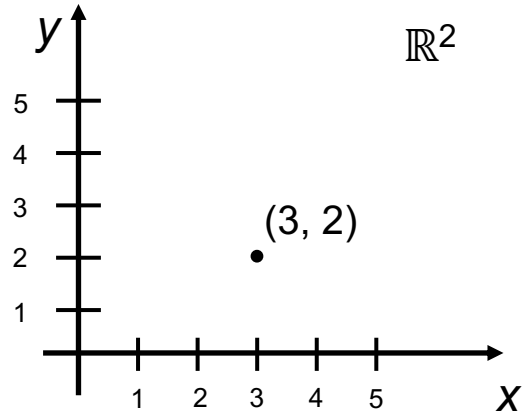
How to extend linearity to **several variables** (x_1, \dots, x_n) ? (ex: dose, weight,...)

Multiple variables = vectors

- a **single** (real) number is called a **scalar** : 1, -2, 3.5, 5/7, π , etc...
- an ordered set of numbers is called a **vector**: (x_1, x_2, x_3) , $(2, -1, 5) \neq (-1, 2, 5)$
- mathematically, it's an element of \mathbb{R}^n , n is called the **dimension**
- a vector can be written as **row** or **column**

$(2, -1, 5)$

$$\begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix}$$



Operations on vectors

- **Addition** of two vectors: $(x_1, \dots, x_n) + (y_1, \dots, y_n) = (x_1 + y_1, \dots, x_n + y_n)$

$$(2, -1, 5) + (-1, 3, 2) = (1, 2, 7)$$

- **Multiplication** of two vectors? $(x_1, \dots, x_n) * (y_1, \dots, y_n) = (x_1 y_1, \dots, x_n y_n)$?

- **Multiplication** by a scalar: $\lambda (x_1, \dots, x_n) = (\lambda x_1, \dots, \lambda x_n)$. $3 (2, -1, 5) = (6, -3, 15)$

\Rightarrow vector space \mathbb{R}^n

$$f : \begin{array}{ccc} \mathbb{R}^n & \rightarrow & \mathbb{R} \\ x = (x_1, \dots, x_n) & \mapsto & f(x) = f(x_1, \dots, x_n) \end{array}$$

f linear?

$$f(x + y) = f(x) + f(y) \quad f(\lambda x) = \lambda f(x)$$

$$\Rightarrow \exists a = (a_1, \dots, a_n), f(x) = a_1 x_1 + \dots + a_n x_n := \langle a, x \rangle$$

Linear combinations

- If two vectors x and y are such that $y = \lambda x$ for $\lambda \in \mathbb{R}$, y and x are **colinear**

\Rightarrow they carry the same information

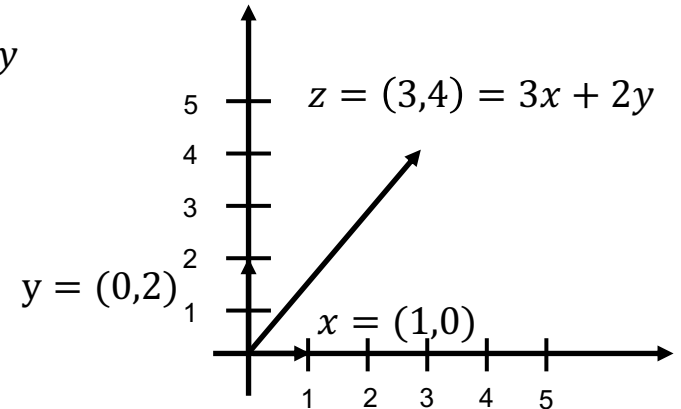
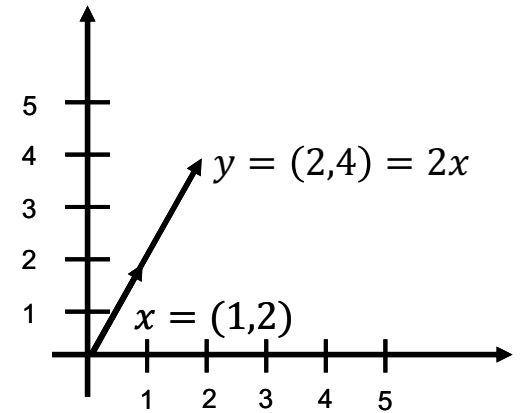
| x | y |
|--------------|-----------------|
| Fluorescence | Bioluminescence |
| 8.53E+09 | 1.50E+08 |
| 2.19E+10 | 3.33E+08 |
| 5.20E+09 | 2.25E+08 |
| 1.41E+10 | 2.62E+08 |
| 8.05E+09 | 4.72E+08 |
| 9.51E+09 | 1.79E+09 |
| 1.06E+10 | 9.03E+08 |

- Linear combination** of two vectors x and y : $z = \lambda x + \mu y$

$$\text{BSA} = 0.00718 \times W^{0.425} \times H^{0.725}$$

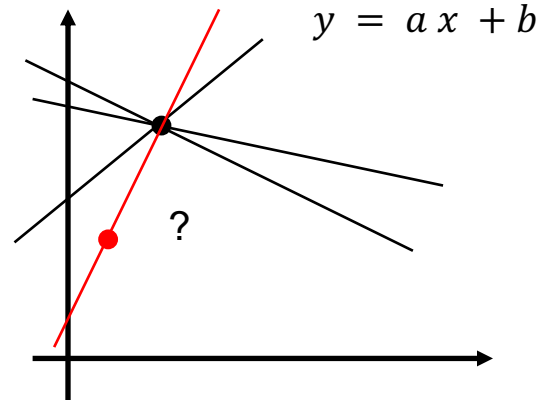
$$\ln(\text{BSA}) = \ln(0.00718) + 0.425 \ln(W) + 0.725 \ln(H)$$

\Rightarrow the three quantities W , H and BSA are redundant



Basis

- n vectors $\{x_1, \dots, x_n\}$ are said to be **linearly independent** if no vector can be expressed as a linear combination of the others
- Thm: In dimension n any vectors $\{x_1, \dots, x_p\}$ with $p > n$ are linearly dependent
 - ⇒ with n observations it is only possible to identify **maximum n parameters**
- A set $\{x_1, \dots, x_p\}$ of vectors is said to **span** \mathbb{R}^n if any vector of \mathbb{R}^n is a linear combination of $\{x_1, \dots, x_p\}$:
$$\forall x \in \mathbb{R}^n, \exists \lambda_1, \dots, \lambda_p \in \mathbb{R} \text{ s.t. } x = \lambda_1 x_1 + \dots + \lambda_p x_p$$
- Thm: In dimension n any set of n linearly independent vectors spans \mathbb{R}^n and is called a **basis**



Matrices

- A matrix is a rectangular array of numbers with a given number of **rows** (m) and **columns** (n)

$$\begin{matrix} & \begin{matrix} 1 & 2 & \dots & n \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ \vdots \\ m \end{matrix} & \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ a_{31} & a_{32} & \dots & a_{3n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \end{matrix} = (a_{i,j})$$

3 columns

$$\begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix}$$

2 rows

Elementary operations

- Similarly as vectors, we can define **addition** and **multiplication by a scalar**

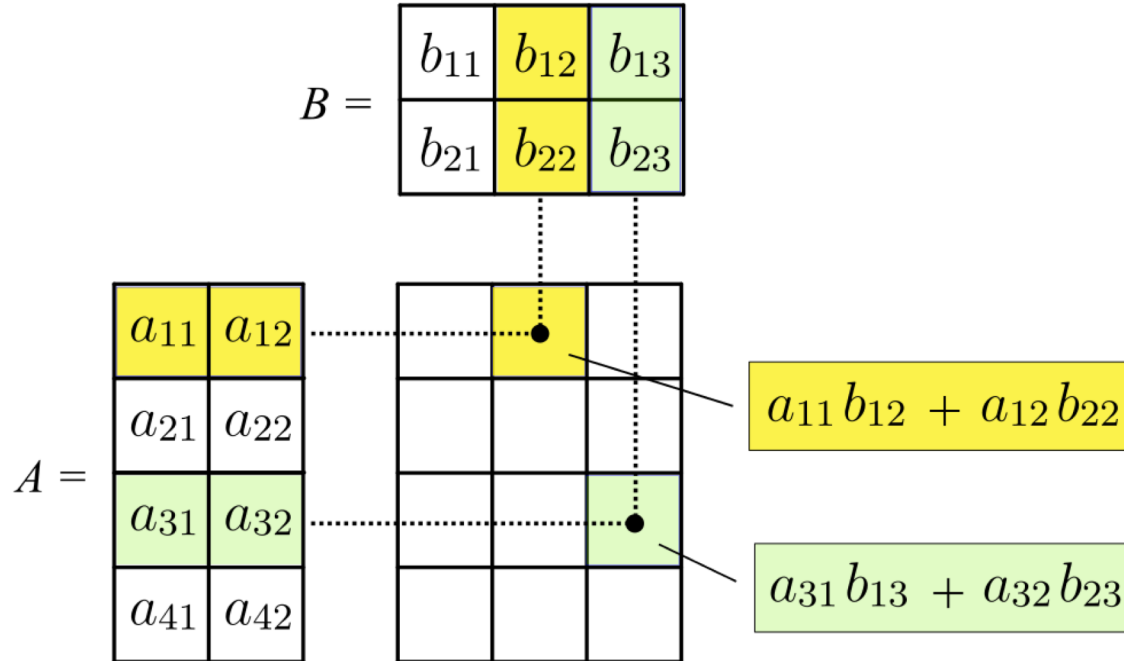
$$\begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix} + \begin{pmatrix} 0 & 2 & 1 \\ 3 & -4 & 5 \end{pmatrix} = \begin{pmatrix} 3 & 1 & 6 \\ 1 & 8 & -2 \end{pmatrix} \quad 2 \cdot \begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix} = \begin{pmatrix} 6 & -2 & 10 \\ -4 & 24 & -14 \end{pmatrix}$$

⇒ the set of m -by- n matrices is a **vector space** $M_{m,n}$ of dimension $m \cdot n$

- **Transposition**

$$\begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix}^T = \begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix}' = \begin{pmatrix} 3 & 2 \\ -1 & 12 \\ 5 & -7 \end{pmatrix}$$

Matrix multiplication



Matrix multiplication

2 rows

3 columns

2 columns

3 rows

2 columns

2 rows

$$\begin{pmatrix} 3 & -1 & 5 \\ -2 & 12 & -7 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 3 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 \times 3 + 0 \times (-1) + 2 \times 5 & \dots \\ \dots & \dots \end{pmatrix} = \begin{pmatrix} 23 & \dots \\ \dots & \dots \end{pmatrix}$$

- The number of **rows of the second matrix** must be the same as the number of **columns of the first matrix**
- It is only possible to multiply a matrix in $M_{m,n}$ by a matrix in $M_{n,p}$ and it gives a $M_{m,p}$ matrix

Special matrices

- Square matrix
$$\begin{pmatrix} a_{1,1} & \cdots & a_{1,n} \\ \vdots & \ddots & \vdots \\ a_{n,1} & \cdots & a_{n,n} \end{pmatrix}$$

- Symmetric matrix: $M^T = M$
$$\begin{pmatrix} 1 & 5 & -3 \\ 5 & 2 & -1 \\ -3 & -1 & -4 \end{pmatrix}$$

- Diagonal matrix
$$\begin{pmatrix} d_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & d_n \end{pmatrix}$$

- Identity matrix
$$I = \begin{pmatrix} 1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & 1 \end{pmatrix}$$

$$\forall M \in M_{n,n}, \quad M \cdot I = I \cdot M = M$$

Example 1: data array

n columns (covariates)



m patients

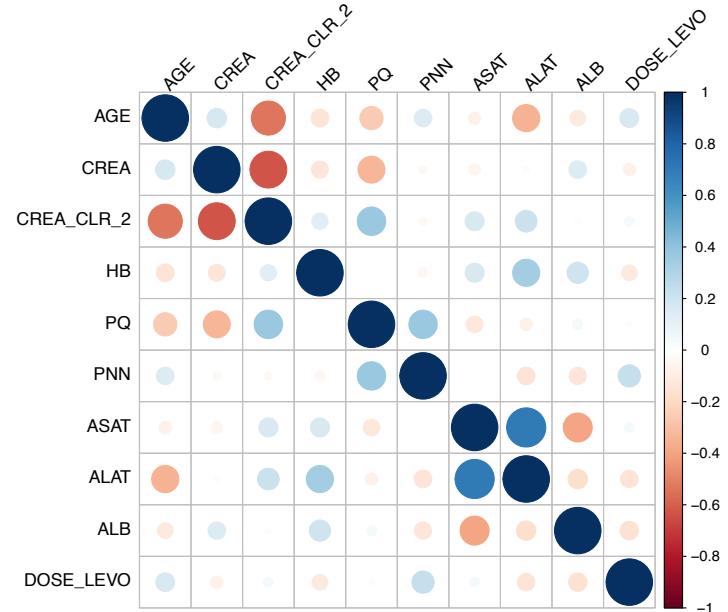


| AGE | BSA | CREA | CREA CLR 2 | HB | PQ | PNN | ASAT | ALAT | ALB | DOSE LEVO |
|-----|------|------|------------|-----|-----|-------|------|------|------|-----------|
| 64 | 2 | 53 | 140 | 106 | 225 | 10.4 | 93 | 101 | 25.6 | 450 |
| 37 | 1.5 | 37 | 195 | 152 | 185 | 5.75 | 25 | 70 | 44 | 300 |
| 61 | 1.75 | 30 | 200 | 112 | 428 | 24.71 | 34 | 32 | 34.8 | 5600 |
| 49 | 2 | 71.6 | 120 | 86 | 138 | 14.06 | 15 | 23 | 38.1 | 1250 |
| 49 | 2 | 56 | 136 | 78 | 103 | 4.03 | 30 | 67 | 36.1 | 0 |
| 33 | 1.79 | 54 | 211 | 79 | 441 | 16.95 | 22 | 34 | 36.6 | 0 |
| 33 | 1.79 | 71 | 152 | 119 | 300 | 5.42 | 30 | 54 | 34.3 | 0 |
| 33 | 1.79 | 52 | 177 | 105 | 146 | 4.86 | 21 | 34 | 34.3 | 0 |
| 36 | 1.87 | 67 | 128 | 129 | 279 | 4.76 | 45.5 | 118 | 39.1 | 0 |
| 47 | 2 | 56 | 149 | 85 | 400 | 8.76 | 15 | 15 | 35.4 | 3450 |
| 47 | 2 | 77 | 130 | 101 | 501 | 8.76 | 12 | 19 | 35.2 | 0 |
| 47 | 2 | 73 | 154 | 99 | 202 | 6.92 | 82 | 16 | 35.4 | 3140 |
| 59 | 1.83 | 71 | 125 | 86 | 22 | 0.2 | 35 | 85 | 37.4 | 2700 |

Example 2: correlation matrix

(x_1, \dots, x_n) n vectors, $C_{i,j} = \text{corr}(x_i, x_j)$

| | AGE | CREA | CREA_CLR_2 | HB | PQ | PNN | ASAT | ALAT | ALB | DOSE_LEVO |
|------------|-------|-------|------------|-------|-------|-------|-------|-------|-------|-----------|
| AGE | 1.00 | 0.18 | -0.54 | -0.15 | -0.25 | 0.14 | -0.07 | -0.35 | -0.11 | 0.16 |
| CREA | 0.18 | 1.00 | -0.63 | -0.13 | -0.34 | -0.03 | -0.06 | -0.02 | 0.14 | -0.07 |
| CREA_CLR_2 | -0.54 | -0.63 | 1.00 | 0.12 | 0.38 | -0.03 | 0.17 | 0.22 | -0.02 | 0.04 |
| HB | -0.15 | -0.13 | 0.12 | 1.00 | 0.01 | -0.04 | 0.17 | 0.34 | 0.21 | -0.11 |
| PQ | -0.25 | -0.34 | 0.38 | 0.01 | 1.00 | 0.38 | -0.13 | -0.07 | 0.05 | -0.02 |
| PNN | 0.14 | -0.03 | -0.03 | -0.04 | 0.38 | 1.00 | 0.00 | -0.15 | -0.14 | 0.23 |
| ASAT | -0.07 | -0.06 | 0.17 | 0.17 | -0.13 | 0.00 | 1.00 | 0.71 | -0.39 | 0.04 |
| ALAT | -0.35 | -0.02 | 0.22 | 0.34 | -0.07 | -0.15 | 0.71 | 1.00 | -0.18 | -0.14 |
| ALB | -0.11 | 0.14 | -0.02 | 0.21 | 0.05 | -0.14 | -0.39 | -0.18 | 1.00 | -0.16 |
| DOSE_LEVO | 0.16 | -0.07 | 0.04 | -0.11 | -0.02 | 0.23 | 0.04 | -0.14 | -0.16 | 1.00 |

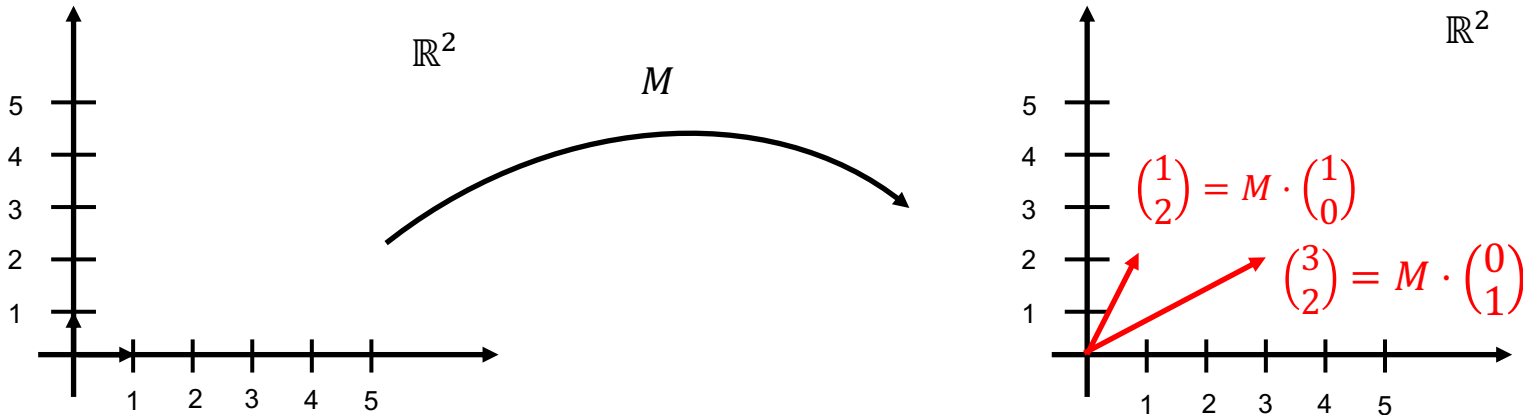


Linear map

- The product of a matrix $M \in M_{n,n}$ with a vector $x \in \mathbb{R}^n$ gives a vector in \mathbb{R}^n .

$$\begin{pmatrix} 1 & 3 \\ 2 & 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

- $M: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is **linear**: $M \cdot (x + y) = M \cdot x + M \cdot y$, $M \cdot (\lambda x) = \lambda M \cdot x$.



Linear system: Equation of a line

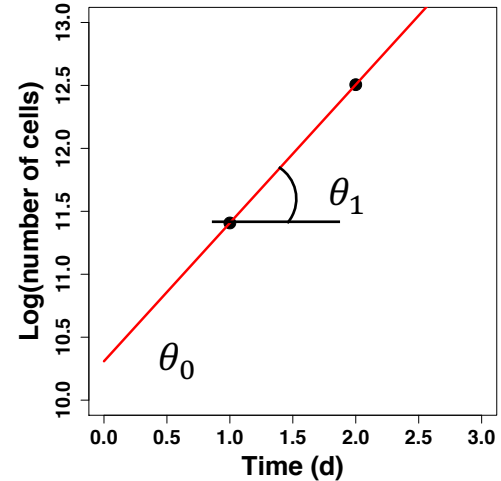
$$y = \theta_0 + \theta_1 t$$

$$\begin{cases} y_1 = 1 \times \theta_0 + t_1 \times \theta_1 \\ y_2 = 1 \times \theta_0 + t_2 \times \theta_1 \end{cases} \Leftrightarrow \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 1 & t_1 \\ 1 & t_2 \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \end{pmatrix}$$

$$y = M \cdot \theta \Rightarrow \theta = M^{-1} \cdot y$$

$$M^{-1} ?? \quad M^{-1} := \frac{1}{M}, \quad M \cdot M^{-1} = \text{"1"} = I$$

is $M \neq \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ sufficient?

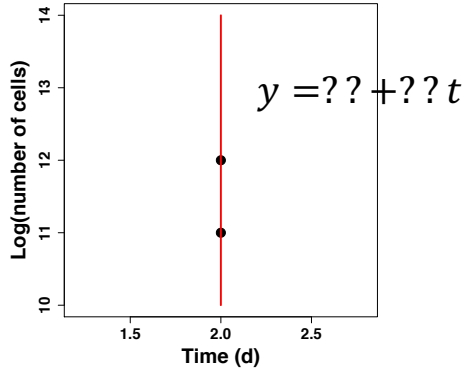


$$\begin{cases} 11.4 = 1 \times \theta_0 + 1 \times \theta_1 \\ 12.5 = 1 \times \theta_0 + 2 \times \theta_1 \end{cases} \Leftrightarrow \begin{pmatrix} 11.4 \\ 12.5 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \end{pmatrix}$$

$$\theta_0 = 10.3, \theta_1 = 1.1$$

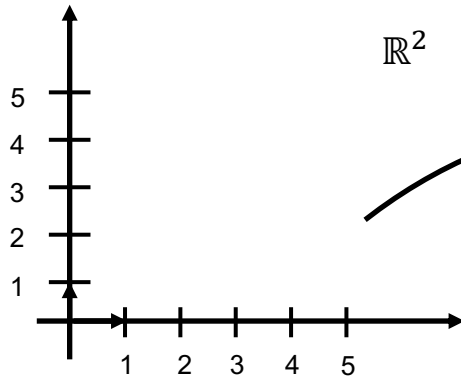
$$\text{Doubling time} = \frac{\ln 2}{\theta_1} \times 24 = 15.1 \text{ hours}$$

Invertible matrix



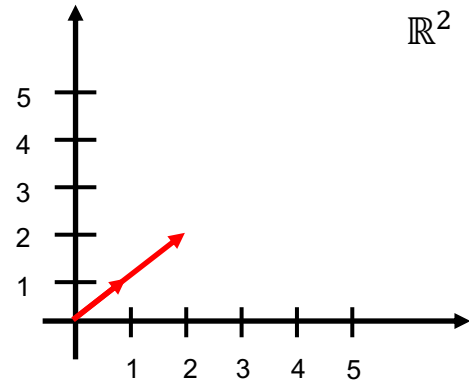
$$\begin{cases} 11 = \theta_0 + 2 \times \theta_1 \\ 12 = \theta_0 + 2 \times \theta_1 \end{cases} \Leftrightarrow \begin{pmatrix} 11 \\ 12 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \end{pmatrix}$$

$M = \begin{pmatrix} 1 & 2 \\ 1 & 2 \end{pmatrix}$ is **not invertible** because its column (and row) vectors are **colinear**



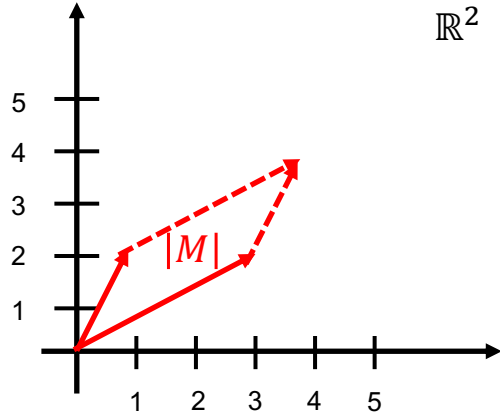
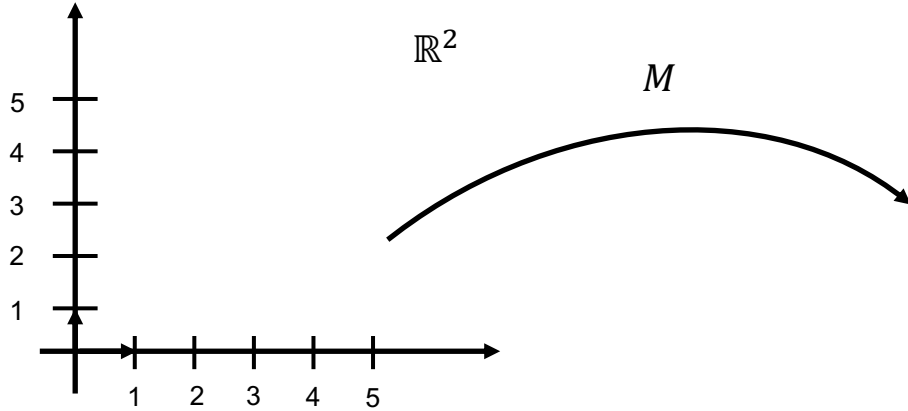
\mathbb{R}^2

M



\mathbb{R}^2

Determinant



- The determinant of M , denoted $|M|$, is the **area of the parallelogram** spanned by the column vectors of M
- For $M = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ it is given by $ad - bc$.
- It can be generalized in any dimension and is a **measure of the colinearity** (and correlation) of the vectors
- $|M| \neq 0 \Leftrightarrow M$ is invertible \Leftrightarrow the column (and row) vectors of M are independent

Linear system: polynomial interpolation

- What if we have 3 points?
- 3 points \Leftrightarrow 3 degrees of freedom \Leftrightarrow 3 parameters

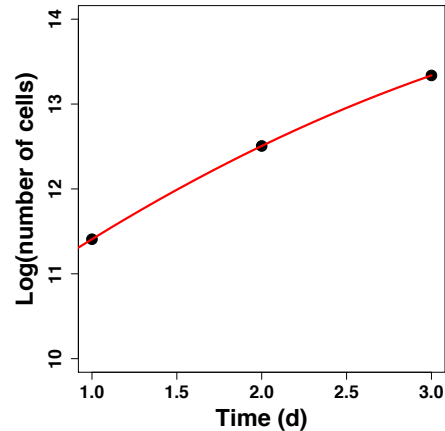
$$y = \theta_0 + \theta_1 t + \theta_2 t^2$$

3 unknowns

3 equations

$$\begin{cases} y_1 = \theta_0 + \theta_1 t_1 + \theta_2 t_1^2 \\ y_2 = \theta_0 + \theta_1 t_2 + \theta_2 t_2^2 \\ y_3 = \theta_0 + \theta_1 t_3 + \theta_2 t_3^2 \end{cases} \Leftrightarrow \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 & t_1 & t_1^2 \\ 1 & t_2 & t_2^2 \\ 1 & t_3 & t_3^2 \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix}$$

$$\Leftrightarrow y = M \cdot \theta \Leftrightarrow \theta = M^{-1} \cdot y$$



$$y = 10 + 1.5t - 0.13t^2$$

Linear system: polynomial interpolation

- 4 points?
- 4 points \Leftrightarrow 4 degrees of freedom \Leftrightarrow 4 parameters

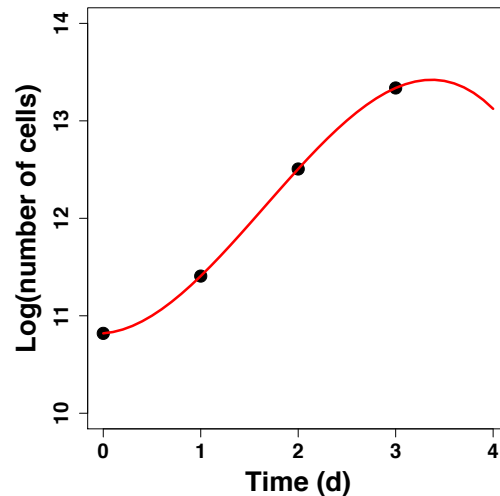
$$y = \theta_0 + \theta_1 t + \theta_2 t^2 + \theta_3 t^3$$

4 unknowns

4 equations

$$\begin{cases} y_1 = \theta_0 + \theta_1 t_1 + \theta_2 t_1^2 + \theta_3 t_1^3 \\ y_2 = \theta_0 + \theta_1 t_2 + \theta_2 t_2^2 + \theta_3 t_2^3 \\ y_3 = \theta_0 + \theta_1 t_3 + \theta_2 t_3^2 + \theta_3 t_3^3 \\ y_4 = \theta_0 + \theta_1 t_4 + \theta_2 t_4^2 + \theta_3 t_4^3 \end{cases} \Leftrightarrow \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \end{pmatrix} = \begin{pmatrix} 1 & 1 & t_1 & t_1^2 \\ 1 & 1 & t_2 & t_2^2 \\ 1 & 1 & t_3 & t_3^2 \\ 1 & 1 & t_4 & t_4^2 \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{pmatrix}$$

\Rightarrow overfit, poor predictive power



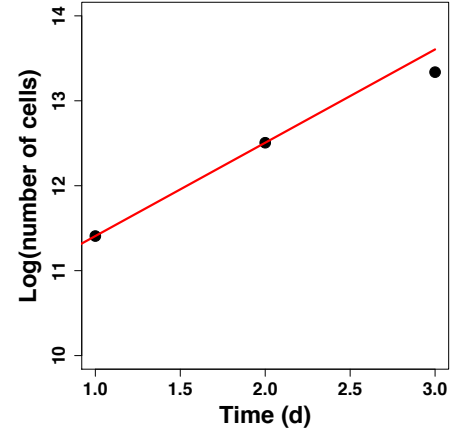
Back to simplicity: line

- How to fit 3 points with one line?

2 unknowns

$$\begin{cases} y_1 = \theta_0 + \theta_1 t_1 \\ y_2 = \theta_0 + \theta_1 t_2 \\ y_3 = \theta_0 + \theta_1 t_3 \end{cases} \Leftrightarrow \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \theta_0 \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \theta_1 \cdot \begin{pmatrix} t_1 \\ t_2 \\ t_3 \end{pmatrix}$$

2 vectors cannot span a space of dimension 3



no solution (in general)

3 equations

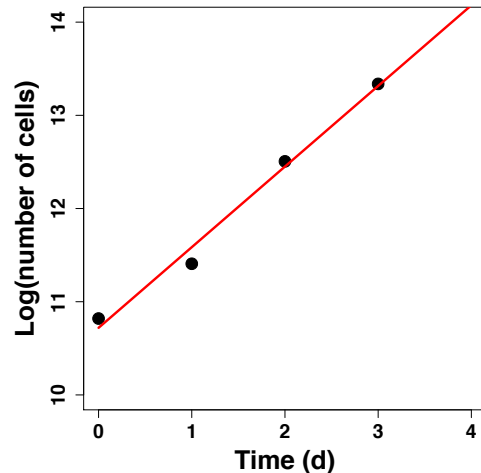
Linear regression

$$y = \theta_0 + \theta_1 t + \varepsilon$$

Question: what is the « best » linear approximation of y ?

$$n \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_n \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \end{pmatrix} \quad \longrightarrow \quad \begin{array}{l} M \text{ rectangular} \\ \text{no solution} \end{array}$$

$$\begin{array}{l} \times M^T (\in M_{2,n}) \left(\begin{array}{l} \Leftrightarrow y = M \cdot \theta \\ \Rightarrow \underbrace{M^T y}_{M_{2,n} \cdot M_{n,1}} = \underbrace{M^T M}_{M_{2,2} \cdot M_{2,1}} \cdot \theta \end{array} \right) \quad \longrightarrow \quad \begin{array}{l} \text{one unique solution} \\ \text{(if the square matrix } M^T M \text{ is invertible)} \end{array} \\ \\ M_{2,1} \qquad \qquad M_{2,2} \cdot M_{2,1} \end{array}$$



$$\hat{\theta} = (M^T M)^{-1} M^T y$$

Least-squares

- $\hat{\theta}$ is the value of the parameter vector θ that minimizes the **sum of squared residuals**

$$SS = \sum_{i=1}^n (y_i - (\theta_0 + \theta_1 t_i))^2 \qquad \widehat{\theta}_1 = \frac{\sum (y_i - \bar{y})(t_i - \bar{t})}{\sum (t_i - \bar{t})^2}, \quad \widehat{\theta}_0 = \bar{y} - \widehat{\theta}_1 \bar{t}$$

- It is called the **least-squares estimator** of the linear model
- It corresponds to the **projection of $y \in \mathbb{R}^n$** on the column space of the matrix M , i.e the space spanned by $\mathbf{1} = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix}$ and $t = \begin{pmatrix} t_1 \\ \vdots \\ t_n \end{pmatrix}$, of dimension 2 (2 linearly independent vectors)
- It **regresses** the information contained in the dependent variable y on the independent variables $\mathbf{1}$ (constants) and t

Quadratic form: 1D. Normal distribution

- One complexity step beyond linearity:
quadratic relationship

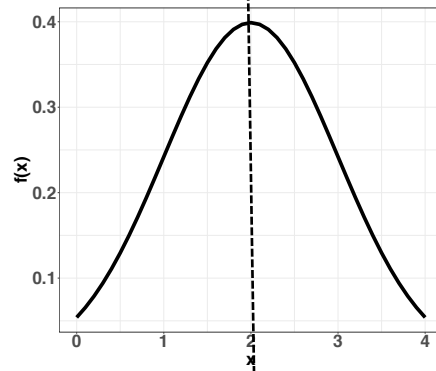
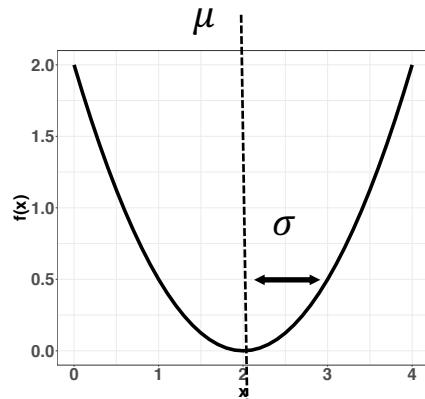
$$f: \begin{array}{l} \mathbb{R} \rightarrow \mathbb{R} \\ x \mapsto ax^2 \end{array}$$

$$f(x) = \frac{(x - \mu)^2}{2\sigma^2}$$

- Normal distribution

$$f(x) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

in 2D??



Quadratic form 2D: matrix form

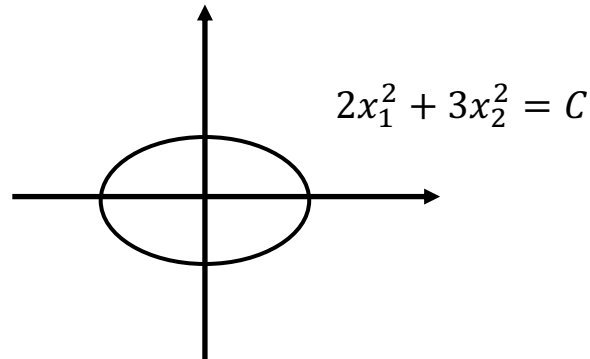
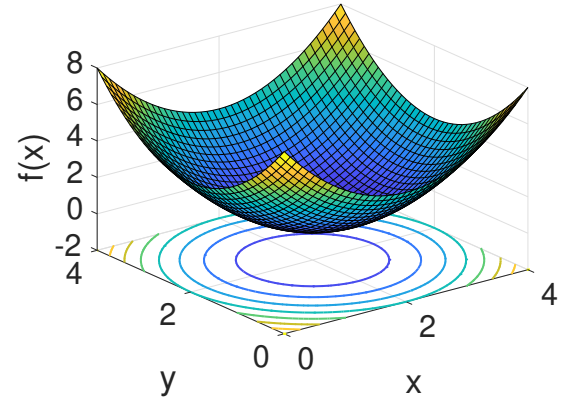
- Quadratic form in \mathbb{R}^2

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$
$$x = (x_1, x_2) \mapsto ax_1^2 + 2bx_1x_2 + cx_2^2$$

$$f(x) = (x_1, x_2) \cdot \begin{pmatrix} a & b \\ b & c \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = x^T \cdot M \cdot x$$

- M is a **symmetric** matrix
- If M is **diagonal**

$$(x_1, x_2) \cdot \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 2x_1^2 + 3x_2^2$$



Covariance/correlation matrix

- Two (or more) variables x and y (ex: V and CL)

$$\Sigma = \begin{pmatrix} \text{Var}(x) & \text{Cov}(x, y) \\ \text{Cov}(x, y) & \text{Var}(y) \end{pmatrix}$$

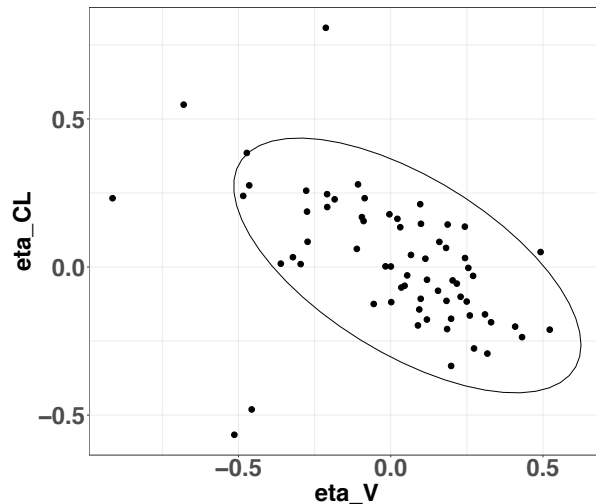
$$\text{Cov}(x, y) = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

- Correlation matrix

$$R = \begin{pmatrix} 1 & r(x, y) \\ r(x, y) & 1 \end{pmatrix}$$

$$r(x, y) = \frac{\text{Cov}(x, y)}{\sigma_x \sigma_y}$$

note: $\hat{\theta}_1 = r(x, y) \frac{\sigma_y}{\sigma_x}$



Multivariate normal distribution

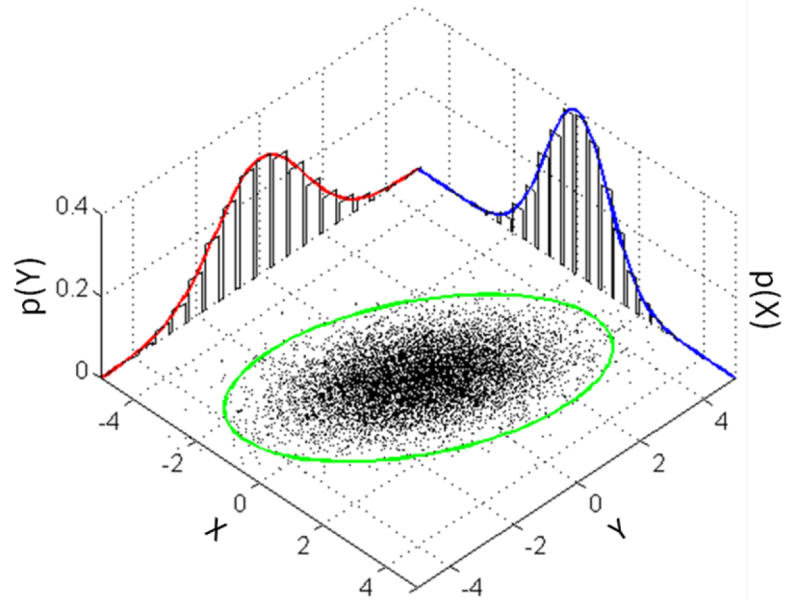
- Generalization of the normal distribution in dimension n

$$x \rightarrow \mathbf{x} = (x, y), \mu \rightarrow \boldsymbol{\mu} = (\mu_1, \mu_2)$$

$$\sigma^2 \rightarrow \Sigma = \begin{pmatrix} \text{Var}(x) & \text{Cov}(x, y) \\ \text{Cov}(x, y) & \text{Var}(y) \end{pmatrix}$$

$$\frac{(x - \mu)^2}{2\sigma^2} \rightarrow \frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})$$

$$f(\mathbf{x}) = \frac{1}{2\pi\sqrt{|\Sigma|}} e^{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})}$$



Eigenvalues and eigenvectors

- An **eigenvector** $v \in \mathbb{R}^n$ associated to an **eigenvalue** $\lambda \in \mathbb{R}$ is defined by

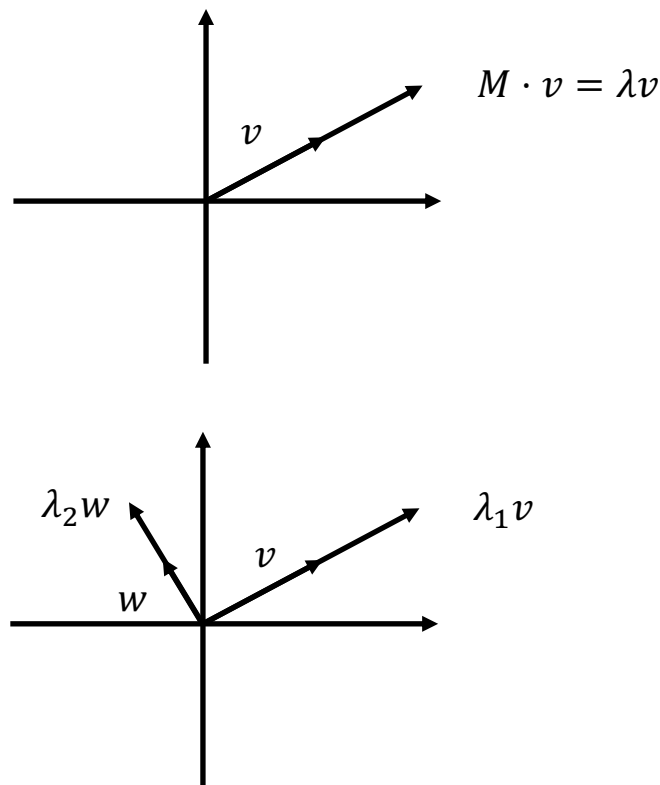
$$M \cdot v = \lambda v$$

- In a basis of eigenvectors, M is **diagonal**

$$M \triangleq D = \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_n \end{pmatrix}$$

- Thm: If M is a symmetric matrix, it is **diagonalizable** (in an orthogonal basis)

$$M = PDP^{-1}, \quad P^T P = I, \quad P = (v, w)$$



Example

$$\Sigma = \begin{pmatrix} 2.98 & -4.65 \\ -4.65 & 64.1 \end{pmatrix}$$

$$\Sigma = P \cdot \begin{pmatrix} 64.4 & 0 \\ 0 & 2.63 \end{pmatrix} P^{-1}$$

- first **eigenvector** = direction of the data of maximal variance
- first **eigenvalue** = variance of the data in this direction

