

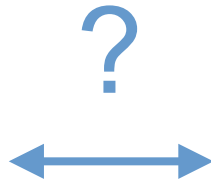
Nonlinear regression

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Master 2 Pharmacocinétique

1. Fitting a model

Data



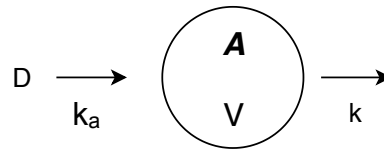
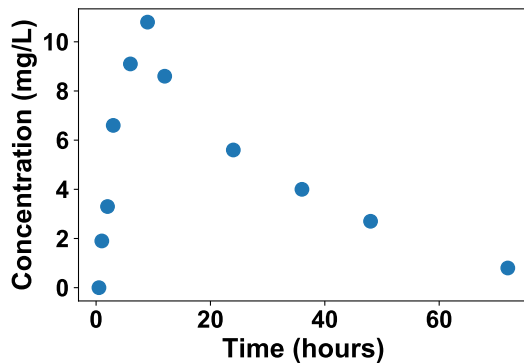
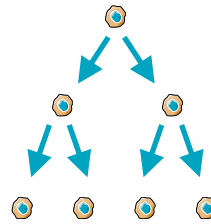
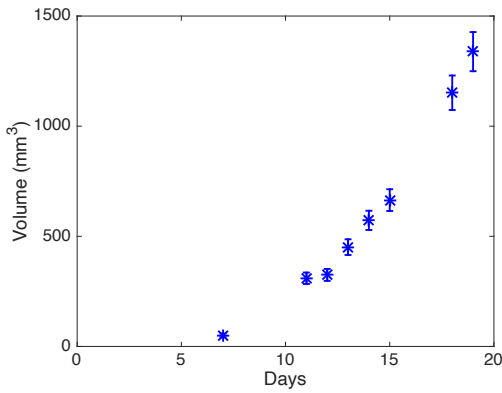
Theory



Mathematical model

$$M : \begin{matrix} \mathbb{R} \times \mathbb{R}^p & \rightarrow & \mathbb{R} \\ (t, \theta) & \mapsto & M(t, \theta) \end{matrix}$$

$$M(t, \theta) = e^{\theta t}$$



$$\begin{cases} \frac{dA_a}{dt} = -k_a A_a \\ \frac{dA}{dt} = k_a A_a - kA \\ A_a(t=0) = D, \quad A(t=0) = 0 \end{cases}$$

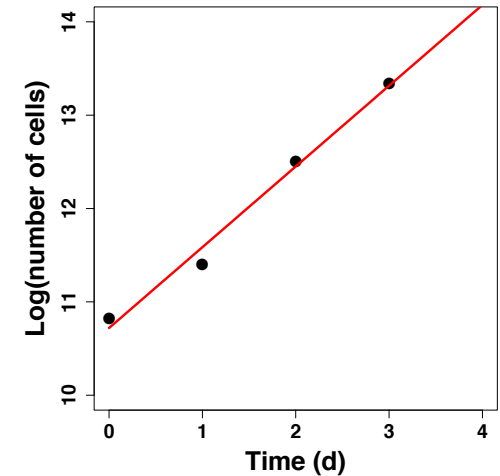
$$C(t) = \frac{A(t)}{V}$$

1.1 Fitting a *linear* model

Linear regression

$$y = \theta_0 + \theta_1 t + \varepsilon$$

Question: what is the « best » linear approximation of y ?



$$n \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_n \end{pmatrix} \cdot \begin{pmatrix} \theta_0 \\ \theta_1 \end{pmatrix} \longrightarrow M \text{ rectangular} \\ \text{no solution}$$

$$\begin{aligned} & \Leftrightarrow y = M \cdot \theta \\ \times M^T (\in M_{2,n}) \left(\begin{aligned} & \Rightarrow M^T y = \underbrace{M^T M}_{M_{2,n} \cdot M_{n,1}} \cdot \theta \longrightarrow \text{one unique solution} \\ & \underbrace{M_{2,n} \cdot M_{n,2} \cdot M_{2,1}}_{M_{2,2} \cdot M_{2,1}} \end{aligned} \right) \\ & \text{(if the square matrix } M^T M \text{ is invertible)} \end{aligned}$$

$$\hat{\theta} = (M^T M)^{-1} M^T y$$

1.2 General theory

Formalism

- **Observations:** n couples of points (t_j, y_j) , with $y_j \in \mathbb{R}$ (or \mathbb{R}^m).

We will denote $y = (y_1, \dots, y_n) \in \mathbb{R}^n$ and $t = (t_1, \dots, t_n)$.

- **Structural model:** a function

$$M : \begin{array}{ccc} \mathbb{R} \times \mathbb{R}^p & \rightarrow & \mathbb{R} \\ (t, \theta) & \mapsto & M(t, \theta) \end{array}$$

- The (unknown) vector of **parameters** $\theta \in \mathbb{R}^p$

Goal = find θ

Statistical model

$$y_j = M(t_j; \theta^*) + e_j$$

- « True » parameter θ^*
- $e_j = \mathbf{error}$ = measurement error + structural error
- See (y_1, \dots, y_n) as realisations of **random variables**

$$Y_j = M(t_j; \theta^*) + \varepsilon_j$$

$Y_j, \varepsilon_j = \text{r.v.}$

$y_j, e_j = \text{realizations}$

- $(y_1, \dots, y_n) = \mathbf{sample}$ with probability density function $p(y | \theta^*)$
- An **estimator** of θ^* is a random variable function of Y , denoted $\hat{\theta}$:

$$\hat{\theta} = h(Y_1, \dots, Y_n)$$

Linear least-squares: statistical properties

$$Y = M\theta^* + \varepsilon$$

$$\hat{\theta}_{LS} = \underset{\theta \in \mathbb{R}^p}{\operatorname{argmin}} \|Y - M\theta\|^2 \Leftrightarrow \hat{\theta}_{LS} = (M^T M)^{-1} M^T Y$$

Proposition:

Assume that $\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$, then

$$\hat{\theta}_{LS} \sim \mathcal{N}\left(\theta^*, \sigma^2 (M^T M)^{-1}\right)$$

From this, [standard errors and confidence intervals](#) can be computed on the parameter estimates

$$se(\hat{\theta}_{LS,p}) = s \sqrt{(M^T M)^{-1}_{p,p}}$$

$$IC_\alpha(\theta_{LS,p}) = \theta^* \pm t_{n-p}^{\alpha/2} s \sqrt{(M^T M)^{-1}_{p,p}}$$

$$s^2 = \frac{1}{n-p} \|y - M\hat{\theta}_{LS}\|^2$$

Statistical test for the model parameters

$$\hat{\theta} \sim \mathcal{N} \left(\hat{\theta}^*, \sigma^2 (M^T M)^{-1} \right)$$

For $k = 1, 2, \dots, p$

$$t_k = \frac{\theta_k - \theta_k^*}{se_k}$$

t-distribution with $n - p$ degrees of freedom

⇒ t-test (Wald test)

$$H_0 : \ll \beta_k = 0 \gg \text{ versus } H_1 : \ll \beta_k \neq 0 \gg$$

Under the null hypothesis, $t_{stat} = \frac{\hat{\beta}_k}{se_k}$ follows a t-distribution with $n - d$ degrees of freedom

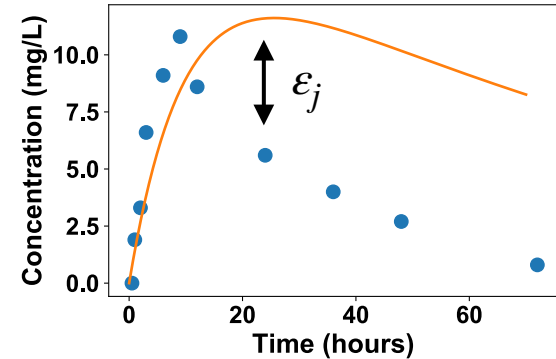
p-value:

$$\mathbb{P} \left(|t_{n-p}| \geq t_{stat} \right) = 2 \left(1 - \mathbb{P} \left(t_{n-p} \leq t_{stat} \right) \right)$$

Nonlinear regression: least-squares

$$Y = M(t; \theta^*) + \varepsilon$$

$$\hat{\theta}_{LS} = \operatorname{argmin}_{\theta \in \mathbb{R}^p} \| Y - M(t; \theta) \|^2$$



Linearization: $M(t, \theta) = M(t, \theta^*) + J \cdot (\theta - \theta^*) + o(\theta - \theta^*)$, $J = D_{\theta}M(t, \theta^*)$

Proposition:

Assume $\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$. Then, for large n , approximately

$$\hat{\theta}_{LS} \sim \mathcal{N}\left(\hat{\theta}^*, \sigma^2 (J^T J)^{-1}\right)$$

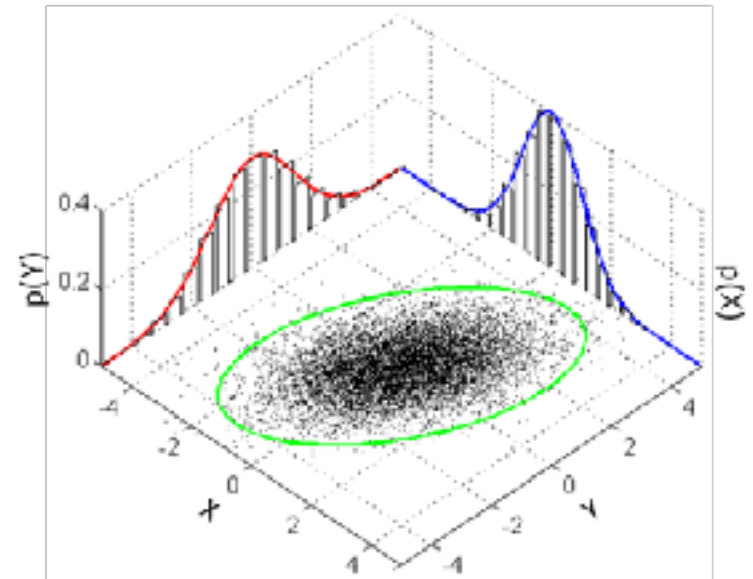
⇒ standard errors, confidence intervals

Sensitivity matrix

$$J = D_{\theta}M(t, \hat{\theta}) = \begin{pmatrix} \frac{\partial M}{\partial \theta_1} (t_1, \hat{\theta}) & \cdots & \frac{\partial M}{\partial \theta_p} (t_1, \hat{\theta}) \\ \vdots & \ddots & \vdots \\ \frac{\partial M}{\partial \theta_1} (t_n, \hat{\theta}) & \cdots & \frac{\partial M}{\partial \theta_p} (t_n, \hat{\theta}) \end{pmatrix}$$

$$\text{var}(\hat{\theta}_{LS}) = \sigma^2 (J^T J)^{-1}$$

- $J^T J$ is a $p \times p$ symmetric matrix
- It is invertible if and only if $\text{rank}(J) = p$
- Column k of $J = 0 \Leftrightarrow M(t, \hat{\theta})$ does not depend on θ_k
- Line i of $J = 0 \Leftrightarrow M(t_i, \hat{\theta})$ does not depend on θ



Nonlinear regression: Likelihood maximization

$$Y = M(t; \theta^*) + \varepsilon$$

The likelihood is defined by

$$L(\theta) = p(y_1, \dots, y_n | \theta) = \prod_{j=1}^n p(y_j | \theta)$$

It is the probability to observe y if the parameter is θ .

The [maximum likelihood estimator \(MLE\)](#) is the value of θ that maximizes the likelihood

$$\hat{\theta}_{MV} = \underset{\theta}{\operatorname{argmax}} L(\theta)$$

Asymptotic properties of the MLE

Proposition:

Under regularity assumptions on L , when $n \rightarrow +\infty$

1. $\hat{\theta}_{MV} \rightarrow \theta^*$ (consistency)
2. $\hat{\theta}_{MV}$ is asymptotically of minimal variance (it reaches the Cramér-Rao bound):

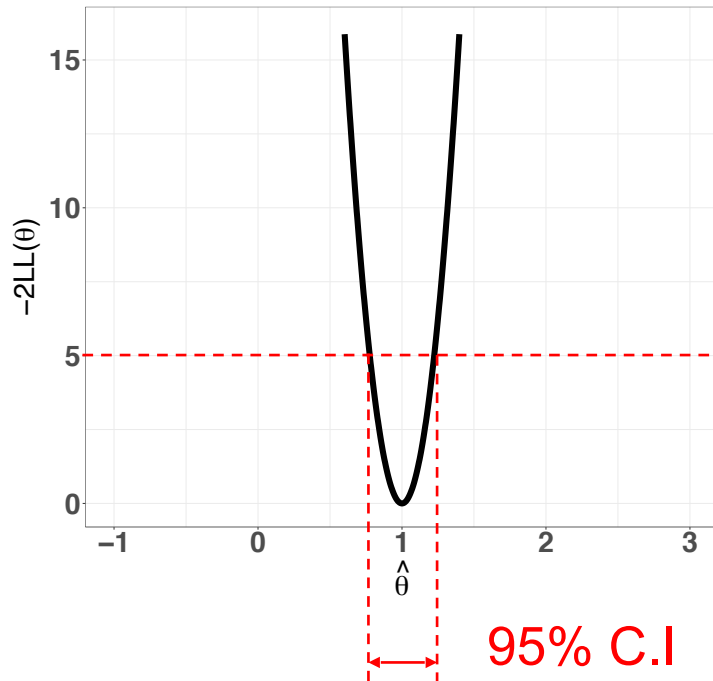
$$\sqrt{n} \left(\hat{\theta}_{MV} - \theta^* \right) \rightarrow \mathcal{N} \left(0, I_{\theta^*}^{-1} \right)$$

where I_{θ^} is the Fisher information matrix*

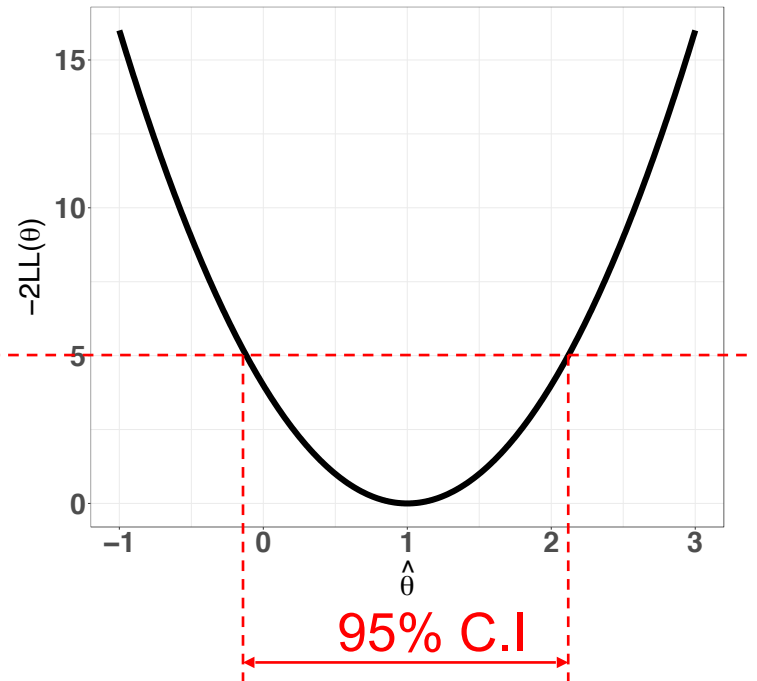
$$(I_{\theta^*})_{j,k} = \mathbb{E} \left[\left\{ \frac{\partial \log(p(Y|\theta^*))}{\partial \theta_j} \right\} \left\{ \frac{\partial \log(p(Y|\theta^*))}{\partial \theta_k} \right\} \right] = \mathbb{E} \left[- \left(\frac{\partial^2 \log(p(Y|\theta^*))}{\partial \theta_j \partial \theta_k} \right) \right].$$

Precision of the estimates

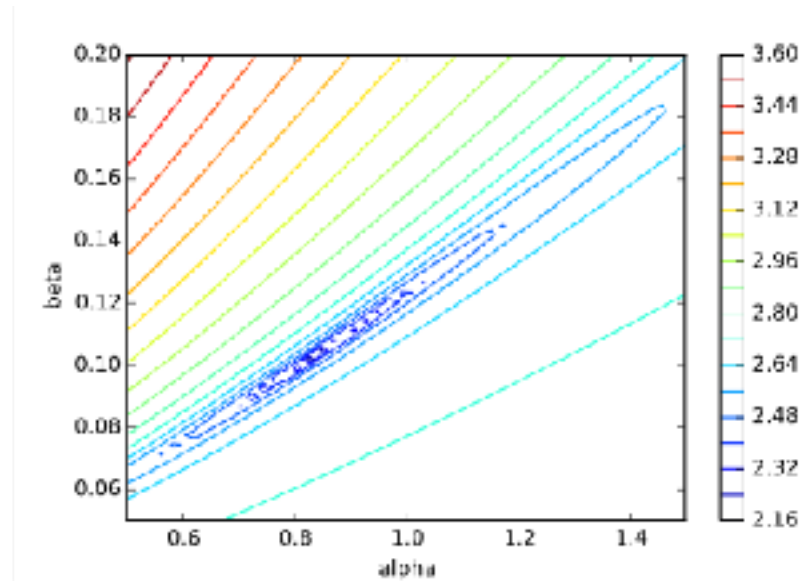
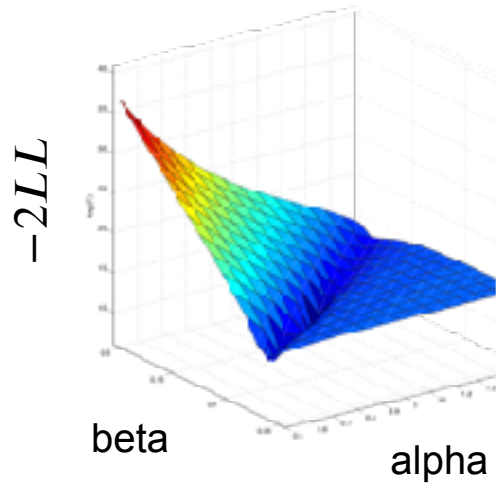
rse = 10%



rse = 50%



Correlation between estimates



Correlation matrix of the estimates

	R.S.E.(%)			
alpha_pop	3.09		1	
beta_pop	5.65	0.9874	1	
b	21.8	0.0055971	0.028118	1

	MIN	MAX	MAX/MIN
Eigen values	0.014	1	1.4e+2

small r.s.e on alpha and beta, but large correlation

MLE: normal errors

$$Y_j = M(t_j; \theta^*) + \varepsilon_j, \quad \varepsilon_j \sim \mathcal{N}(0, \sigma)$$

$$p(y_j | \theta, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(y_j - M(t_j, \theta))^2}{2\sigma^2}}, \quad L(\theta, \sigma) = \frac{1}{(\sigma\sqrt{2\pi})^n} e^{-\frac{\|y - M(t, \theta)\|^2}{2\sigma^2}}$$

Maximize $L(\theta, \sigma) \Leftrightarrow$ minimize $F(\theta, \sigma) = -\log(L(\theta, \sigma))$

$$F(\theta, \sigma) = n \log(\sigma\sqrt{2\pi}) + \frac{\|y - M(t, \theta)\|^2}{2\sigma^2}$$

$$\frac{\partial F}{\partial \sigma}(\hat{\theta}, \hat{\sigma}) = 0 \Rightarrow \hat{\sigma} = \frac{1}{n} \|y - M(t, \hat{\theta})\|^2$$

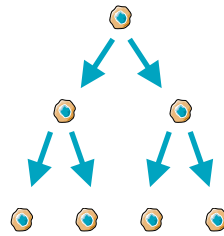
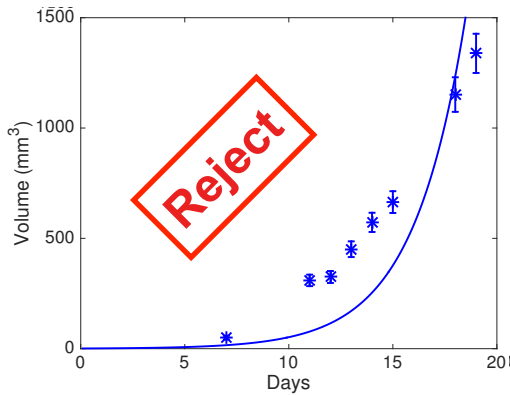
$$\Rightarrow \hat{\theta} = \underset{\theta}{\operatorname{argmin}} \|y - M(t, \theta)\|^2$$

Maximum likelihood \Leftrightarrow Least-squares

Application: tumor growth

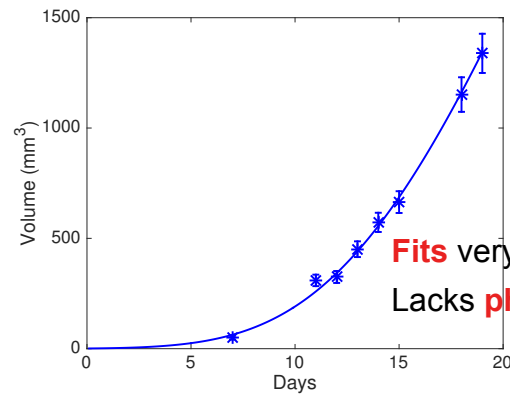
What are **minimal** biological processes able to recover the **kinetics** of (experimental) tumor growth?

Exponential



$$\frac{dV}{dt} = aV$$

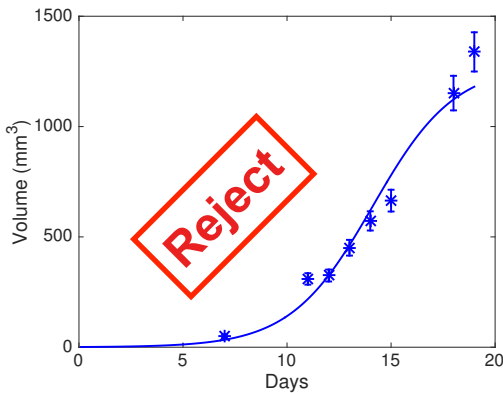
Gompertz



$$\frac{dV}{dt} = \alpha e^{-\beta t} V$$

Fits very well
Lacks **physiological** interpretation

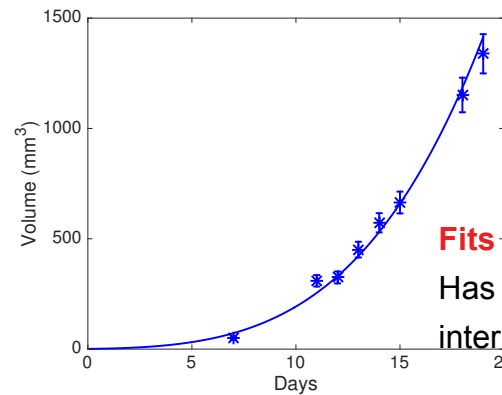
Logistic



Competition

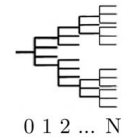
$$\frac{dV}{dt} = aV \left(1 - \frac{V}{K}\right)$$

Power law



$$\frac{dV}{dt} = \alpha V^\gamma$$

Fits very well
Has **physiological** interpretation



Goodness of fit metrics

Sum of Squared Errors

$$SSE^i = \sum_{j=1}^{n^i} \left(\frac{V_j^i - V(t_j^i, \hat{\theta}^i)}{\hat{\sigma}_j^i} \right)^2$$

Akaike Information Criterion

$$AIC^i = -2l(\hat{\theta}^i) + 2p$$



number of parameters

Model	SSE	AIC	RMSE	R ²	p > 0.05	#
Power law	0.164(0.0158 - 0.646) [1]	-18.4(-43.2 - 1.63) [1]	0.415(0.145 - 0.899) [1]	0.97(0.801 - 0.998) [1]	100	2
Gompertz	0.176(0.019 - 0.613)[2]	-16.9(-48.2 - 1.1)[2]	0.433(0.156 - 0.875)[2]	0.971(0.828 - 0.997)[2]	100	2
Logistic	0.404(0.0869 - 0.85)[3]	-5.41(-18.4 - 3.88)[3]	0.665(0.331 - 1)[3]	0.908(0.712 - 0.989)[3]	100	2
Exponential	1.9(0.31 - 3.56)[4]	10.7(-5.38 - 23.1)[4]	1.4(0.595 - 1.95)[4]	0.69(0.454 - 0.944)[4]	15	1

Root Mean Squared Errors

$$RMSE^i = \sqrt{\frac{1}{n-p} SSE^i}$$

R²

$$R^{2,j} = 1 - \frac{\sum_j (V_j^i - V(t_j^i; \hat{\theta}^i))^2}{\sum_j (V_j^i - \bar{V}^i)^2}$$

Parameter values and identifiability

Model	Par.	Unit	Median value (CV)	NSE (%) (CV)
Power law	α	$\text{mm}^{3(1-\gamma)} \cdot \text{day}^{-1}$	0.886 (30.8)	8.17 (52.5)
	γ	-	0.788 (7.56)	2.28 (58.6)
Gompertz	α_0	day^{-1}	1.68 (23.5)	6.11 (82.9)
	β	day^{-1}	0.0703 (28)	8.35 (92.9)
Logistic	a	day^{-1}	0.474 (13.3)	2.93 (23.3)
	K	mm^3	1.92e+03 (36.7)	15.8 (28.7)
Exponential	a	day^{-1}	0.356 (12.9)	2.53 (19.4)
Generalized logistic	a	$[\text{day}^{-1}]$	2555 (148)	2.36e+05 (137)
	K	$[\text{mm}^3]$	4378 (307)	165 (220)
	α	-	0.0001413 (199)	2.36e+05 (137)

NSE = Normalized Standard Error



practical identifiability

$$\hat{\theta} \sim \mathcal{N} \left(\theta^*, \hat{\sigma}^2 (J \cdot J^T)^{-1} \right)$$

$$se(\hat{\theta}^k) = \sqrt{\hat{\sigma}^2 (J \cdot J^T)_{k,k}}$$

Likelihood ratio test

- Comparing two models

$$Y = M_1(t; \theta_1) + \varepsilon_1 \implies L_1(\theta_1, y)$$

$$Y = M_2(t; \theta_2) + \varepsilon_2 \implies L_2(\theta_2, y)$$

- Models have to be nested: $\theta_1 \subset \theta_2$ (ex: M_1 = one compartment, M_2 = two compartments)

$$\begin{aligned} LRT_{stat} &= 2 \left(LL_2(\hat{\theta}_2) - LL_1(\hat{\theta}_1) \right) \\ &= n \log \left(\frac{\sum_{j=1}^n (y_j - M_1(t_j, \theta_1))^2}{\sum_{j=1}^n (y_j - M_2(t_j, \theta_2))^2} \right) \end{aligned}$$

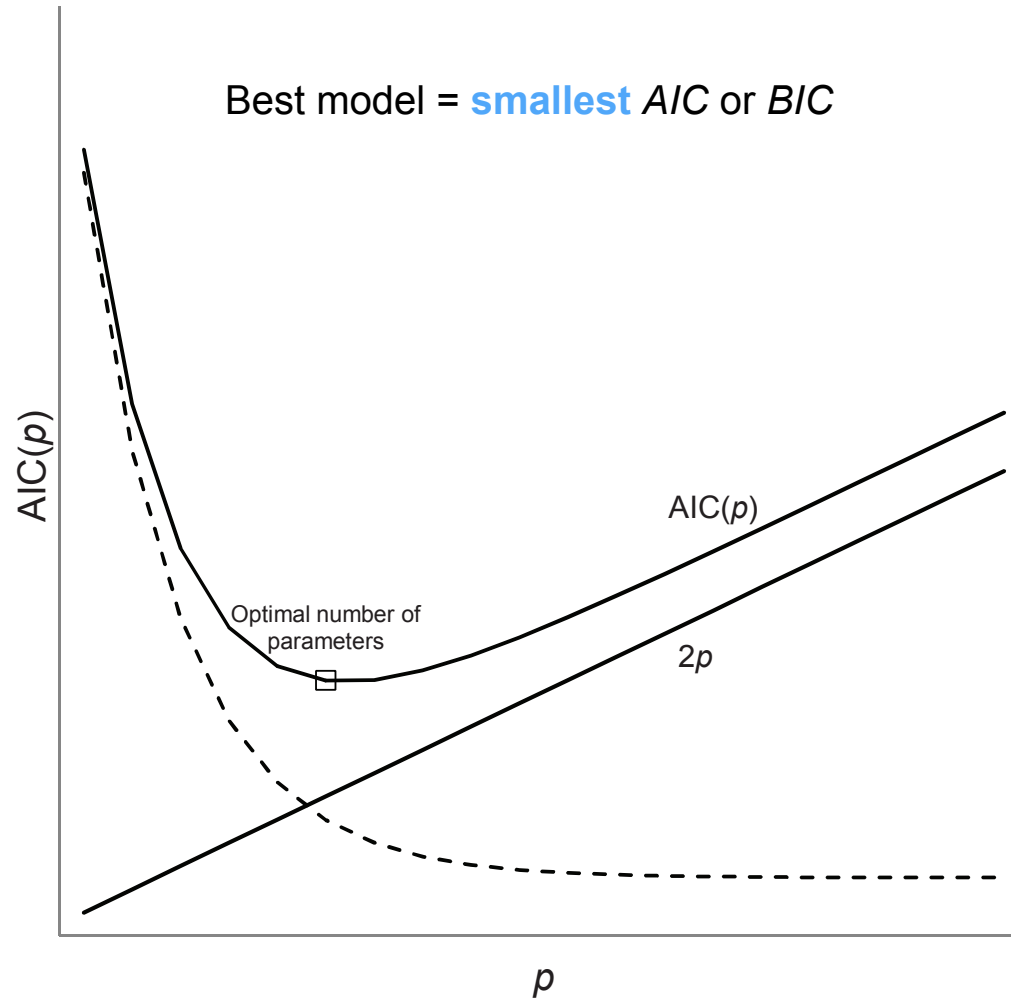
is approximated by a χ^2 distribution
with $p_2 - p_1$ degrees of freedom

Null hypothesis H_0 = « Model M_1 (small model) is better »

Information criteria

$$AIC = -2LL(\hat{\theta}) + 2p$$

$$BIC = -2LL(\hat{\theta}) + \log(n)p$$



Confidence interval and prediction interval

$$Y = M(t; \theta) + \varepsilon$$

- Prediction at new time t_{new} $\widehat{M}_{new} = M(t_{new}, \hat{\theta})$

- Uncertainty on parameter estimate $\hat{\theta} \implies$ **confidence** interval on \widehat{M}_{new}

$$\widehat{M}_{new} \sim \mathcal{N} \left(M_{new}, \text{Var} \left(\widehat{M}_{new} \right) \right)$$

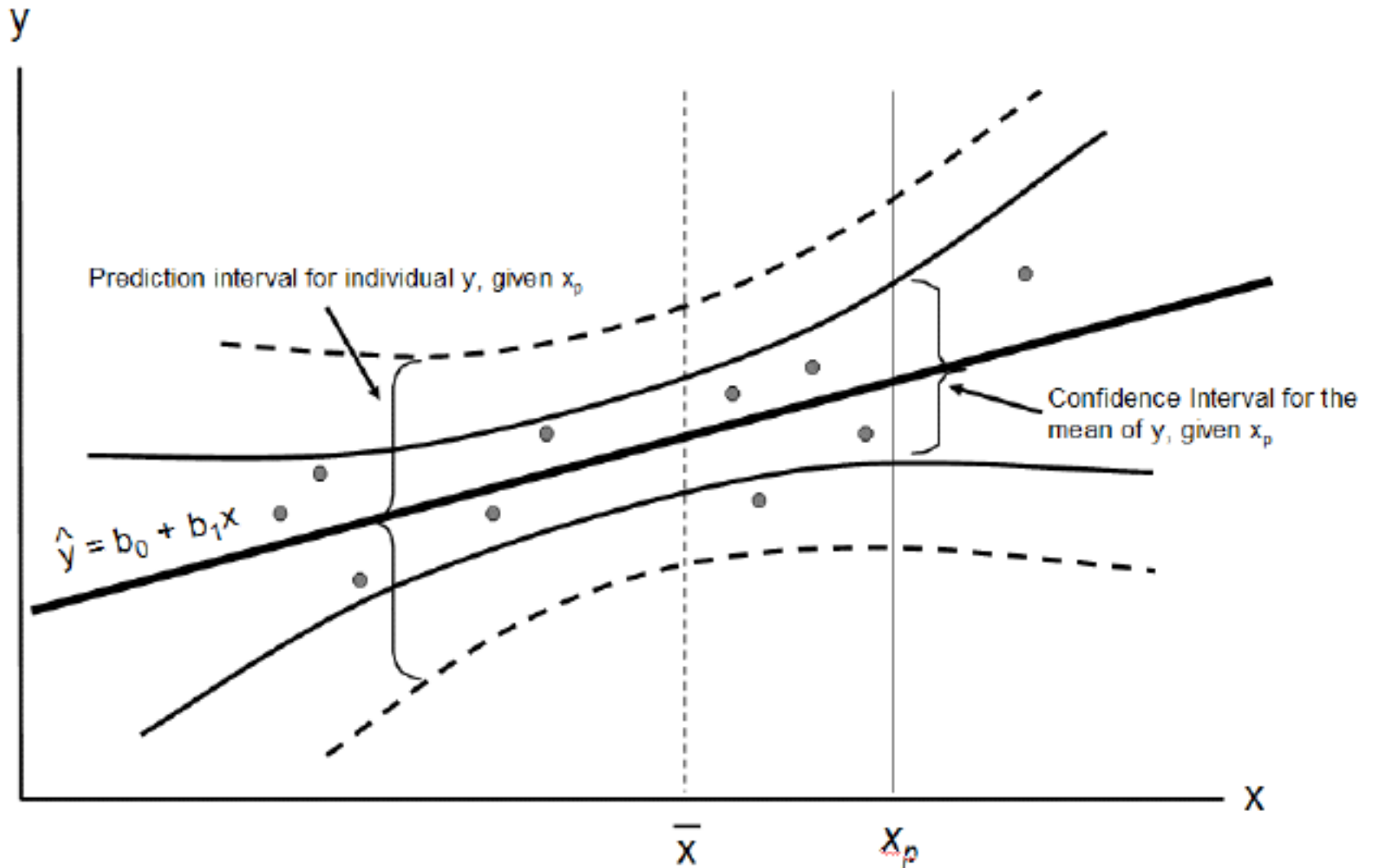
- Uncertainty on parameter estimate $\hat{\theta}$

- + uncertainty on observation ε (e.g. measurement error) \implies **prediction** interval on \widehat{M}_{new}

$$y_{new} = M_{new} + \varepsilon$$

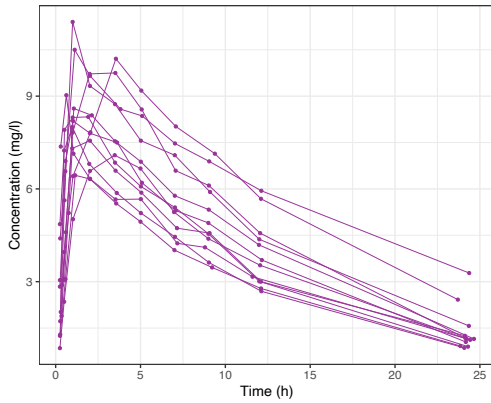
$$y_{new} \sim \mathcal{N} \left(\widehat{M}_{new}, \text{Var} \left(\widehat{M}_{new} \right) + \sigma^2 I \right)$$

Confidence interval vs prediction interval



Mixed-effects modeling

Population data

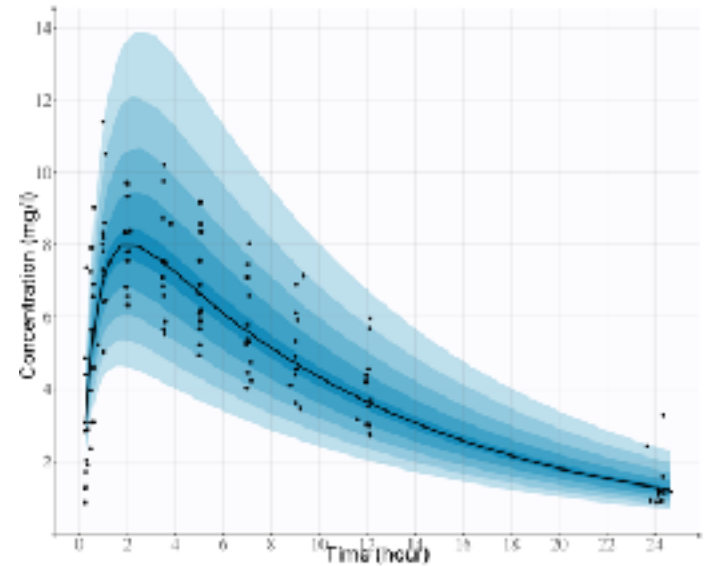


$$\psi^i = \psi_{pop} + \eta^i, \quad \eta^i \sim \mathcal{N}(0, \Omega)$$

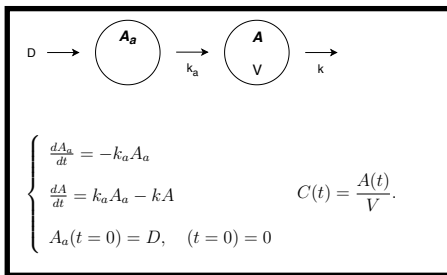
fixed effects

random effects

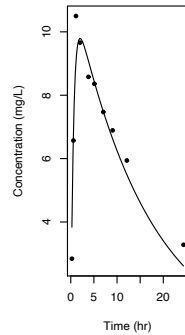
Population fit (MLE)



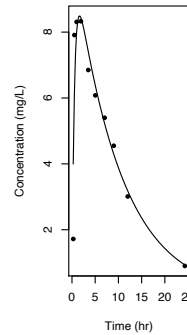
Individual structural model



Subject 1



Subject 2



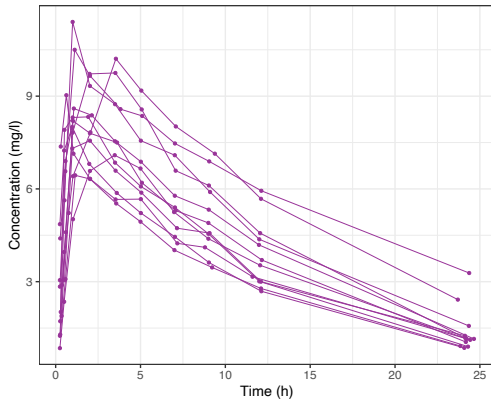
Concentration (mg/L)

Time (hr)

Time (hr)

Population modeling: the two-steps approach

Population data



$$Y^1 = M(t; \theta^1) + \varepsilon$$

$$Y^2 = M(t; \theta^2) + \varepsilon$$

⋮

$$Y^N = M(t; \theta^N) + \varepsilon$$

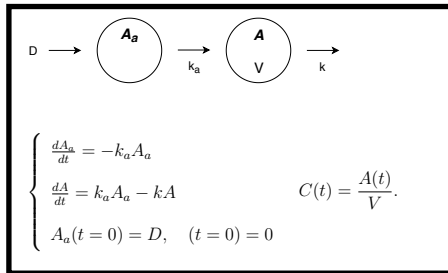


$$\widehat{\theta}_{pop} = \frac{1}{N} \sum_{i=1}^N \theta^i$$

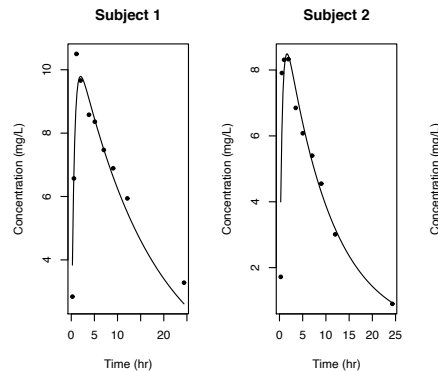
$$\widehat{\Omega} = VCov(\widehat{\theta}^i)$$



Individual structural model



Individual fit



$$\mathcal{N}(\widehat{\theta}_{pop}, \widehat{\Omega})$$

References

- Course « Statistics in Action with R » by Marc Lavielle
<http://sia.webpopix.org/index.html>
- Seber, G. A., & Wild, C. J. (2003). Nonlinear regression. Hoboken (NJ): Wiley-Interscience.